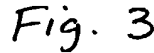


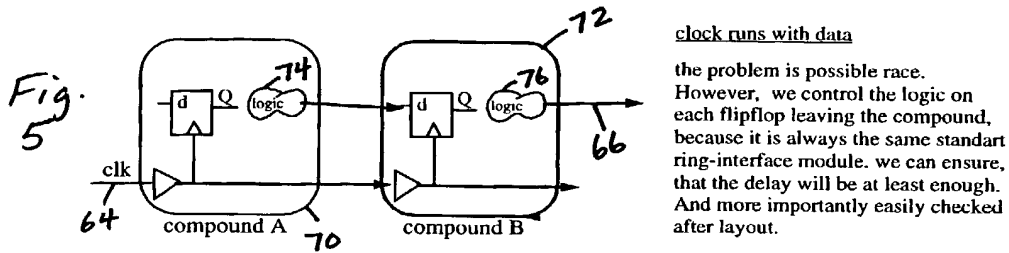
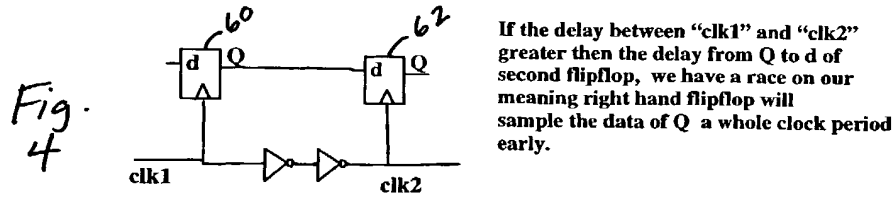
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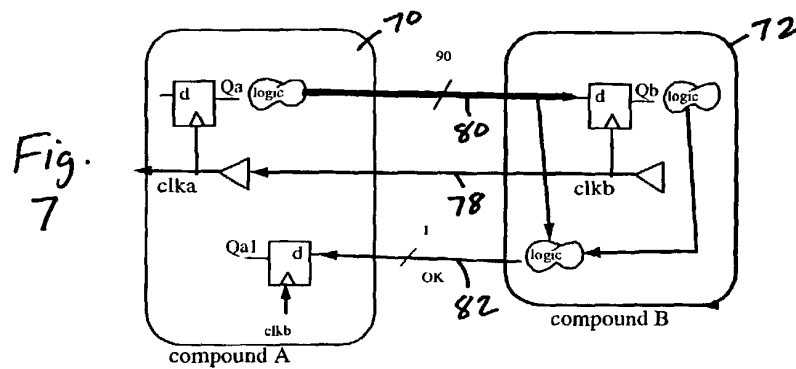
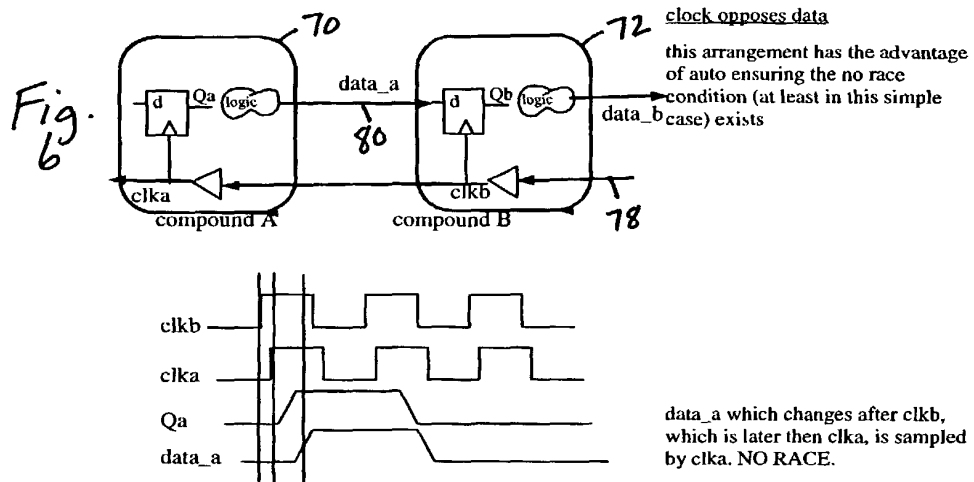
Step1: align incoming address to self (to some power of 2)
Step2: assign the result to self address
Step3: next_addr = self_addr + self_addr_space, // number of register used locally
Step4: send down next_addr

```

Dma needs 16 addrs  
Uart needs 4  
Timer needs 256







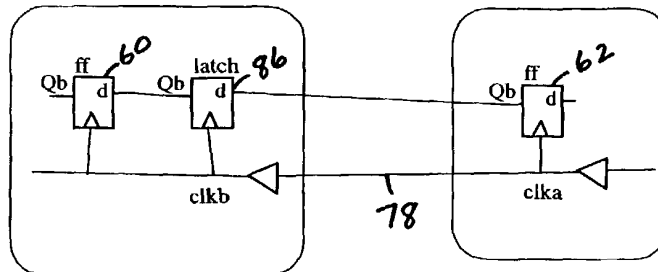
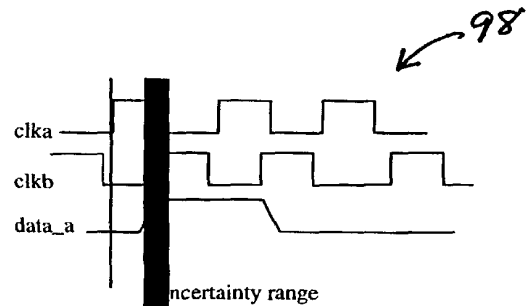
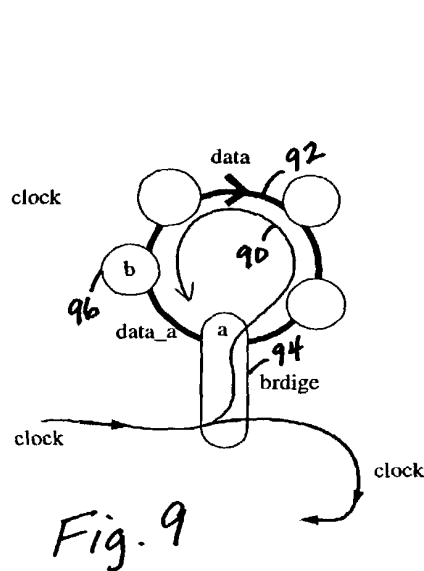


Fig. 8



data\_a leaving the bridge goes to member "b" and there should be sampled by rising of clk\_b. clk\_b lags a lot behind clka of the bridge. As clearly seen from the waveforms, race is eminent. Here we should add latches for all the data lines (~90). Adding latch works however if the delay between clka and clk\_b is less than 75% of cycle time. otherwise the uncertainty kills the usable time. It sets hard limit on the number of ring members. Also keep in mind that latches needed on each OK signal between members of the ring

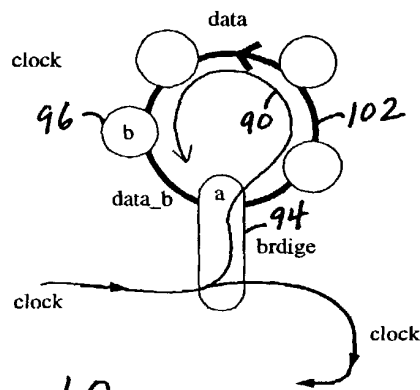
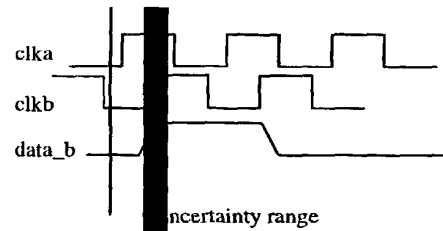


Fig. 10



Here, data\_b leaves member "b" to be sampled by clka in the bridge. But now clkb lags a lot behind clka. This actually works to our advantage; If the lag is smaller then better part of clock cycle. This solution looks better, because between adjacent members, we can take care to delay the datas beyond danger zone of clock delay, the OK signals are covered automatically, and last leg data is also covered. The only signal not safe is the OK from bridge to "b" member. It will need a latch in "b".

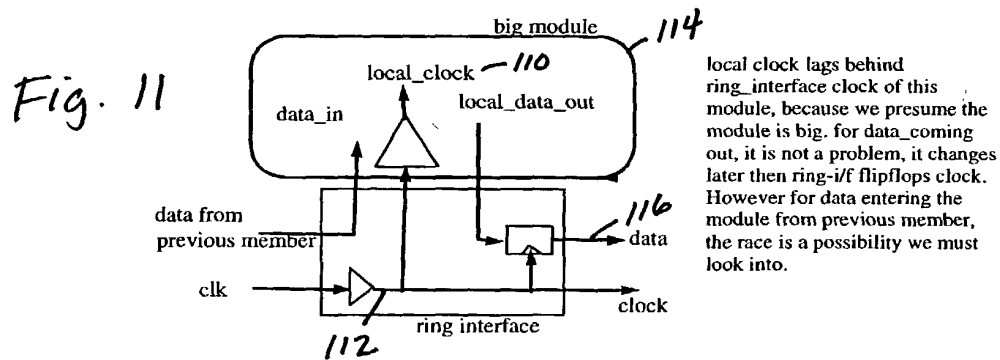
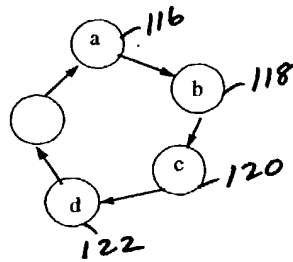


Fig. 12



if module "a" sends a message to module "b", ring works fine. However if most of the traffic is from "c" to "b", this is more expensive in terms of latency.

Another problem is "peak latency". Suppose that, "a" transmits mostly to "d" and "b" mostly to "c". In this case communication between "b" and "c" suffers degradation in case that peak traffic coincide.

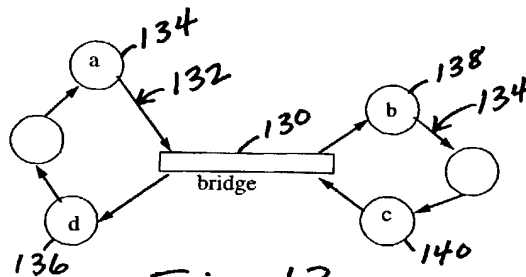
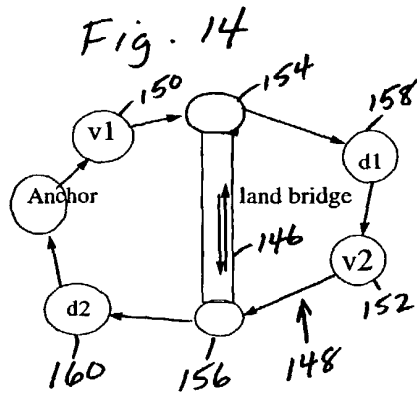
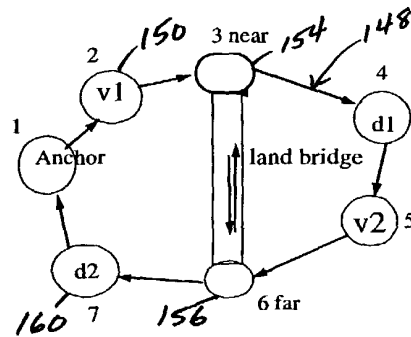


Fig. 13



Land bridge gets its name from the fact that it is a luxury. It spans across connected modules. The idea is simple. When V2 sends message to D1 it gets to one side of the bridge. This side analyzes the destination address and by some magic (explained later) decides to short-cut the path. The message re-appears at the other end of the bridge and gets fast to D1. By same magic, message from V1 to D2 get bypassed also. message from V1 to D1 is treated directly.



Enumeration is started by "Anchor" which assigns address=1 to itself. results of enumeration are labels 1 to 7. land bridge gets two addresses, as if it were not one module. there is "near" end, that got enumeration label "3", and the "far" end marked 6.

Fig. 15





Fig.  
17

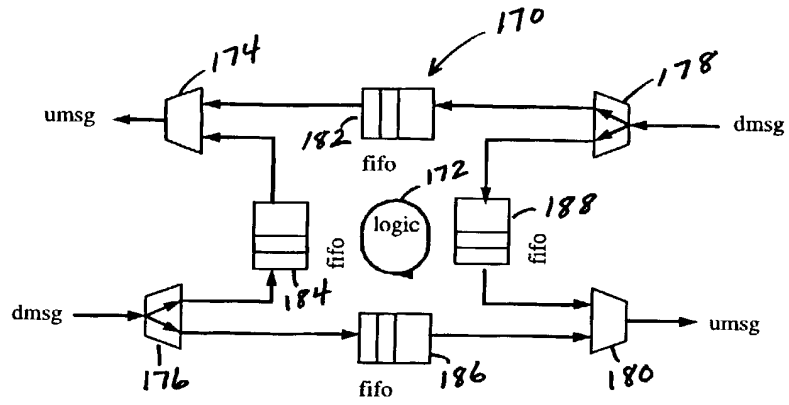
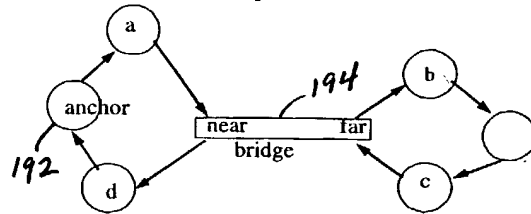


Fig. 18



Bridge takes responsibility for strays, but only at the "far" end. During enumeration, bridge is "polarized" to have near and far end. Near is the end first struck by enumeration message.

So we have exactly one enforcer for each ring.

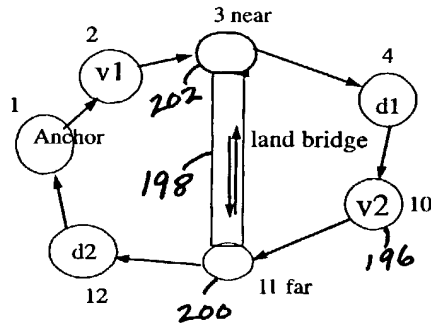


Fig. 19

In land bridge ring, the situation is trickier. If V2 send message to address==5. The land bridge divert at 11/far end. it will re-appear at 3 and start cycling forever.

We have to define an algorithm that will take care of all cases.

Luckily there is a way.

Land Bridge deals only with messages arriving at the far end and being diverted. It marks and monitors only those. Messages arriving at near end, keep their markings. Messages at fdar end going through, are left alone.

Fig. 20

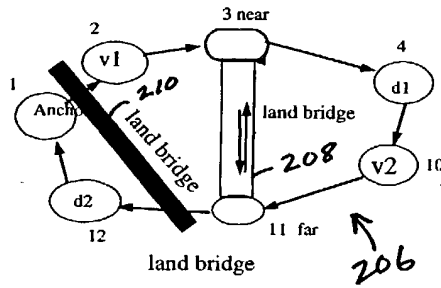


Fig. 21

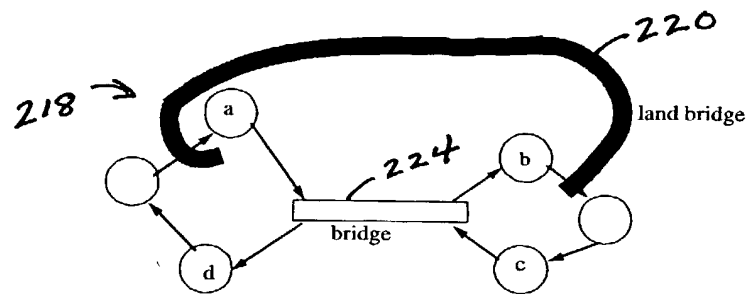
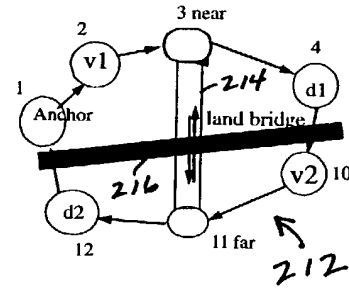
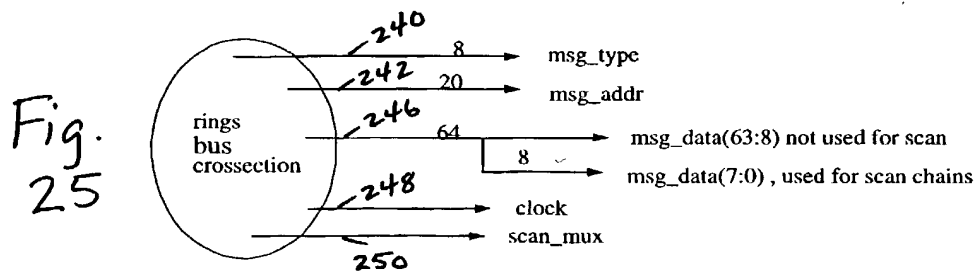
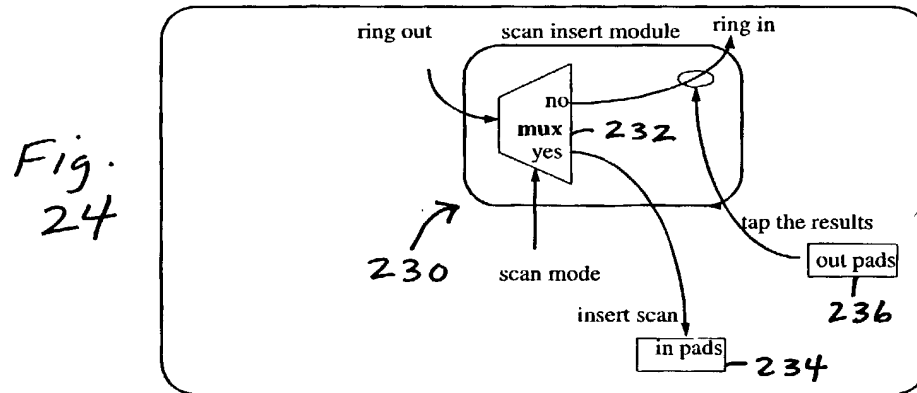
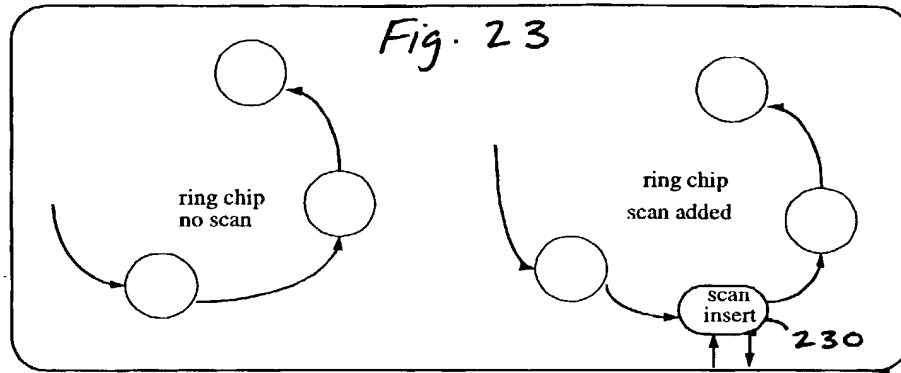
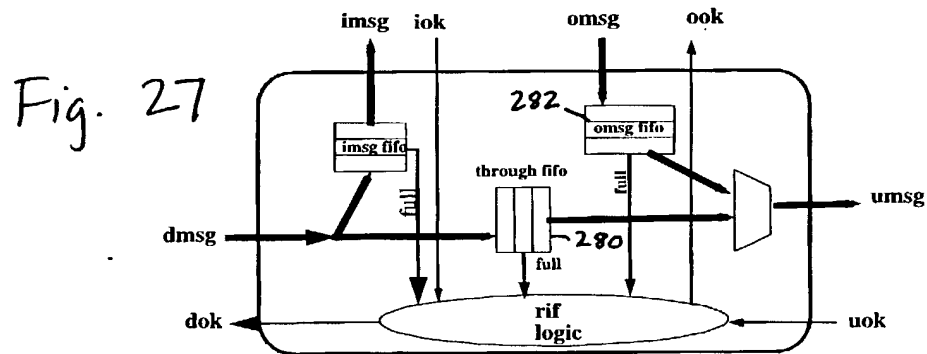
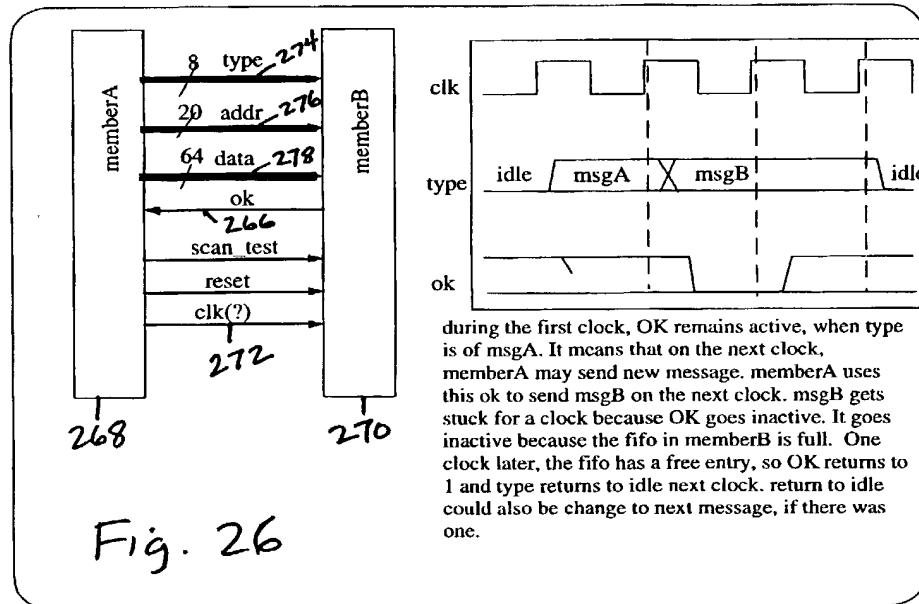


Fig. 22







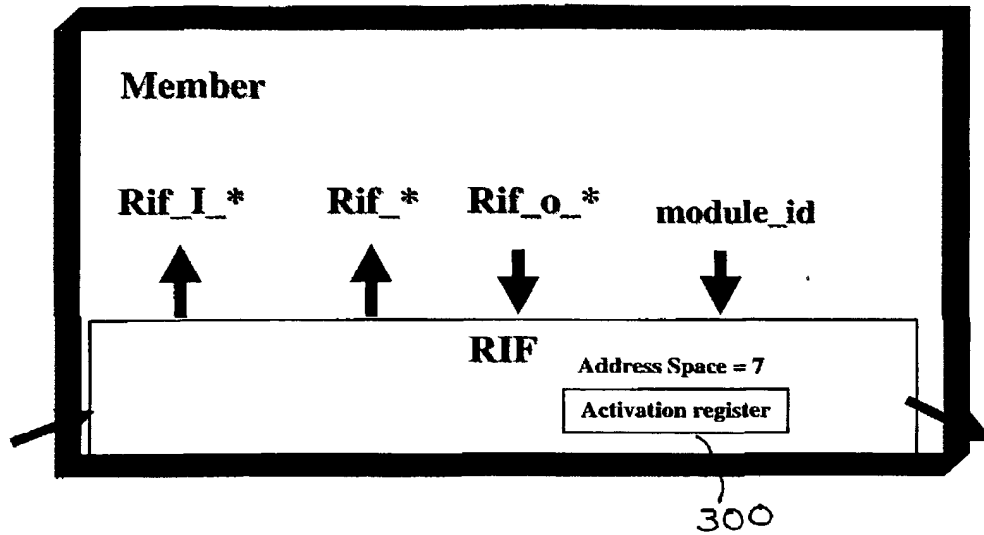


Fig. 30



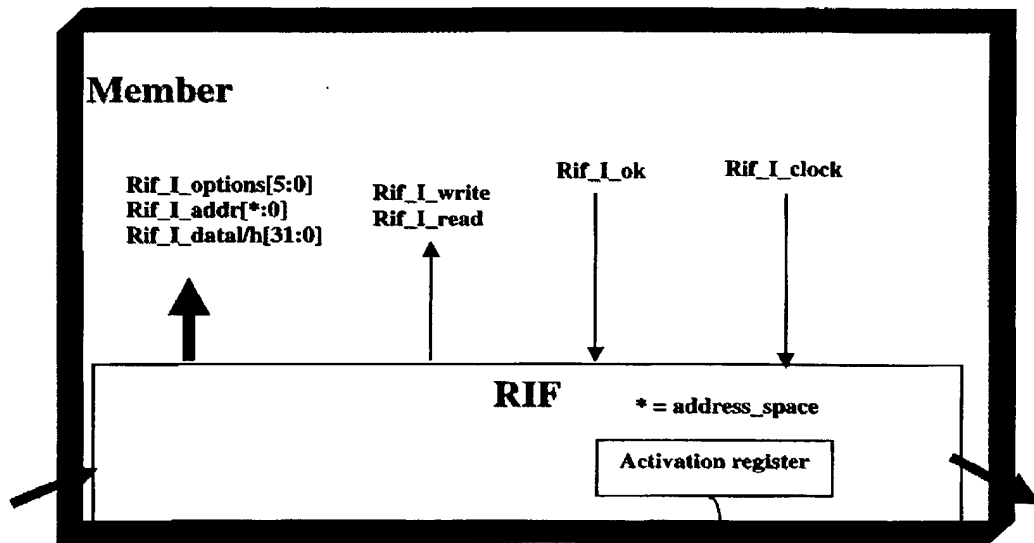


Fig. 31

300

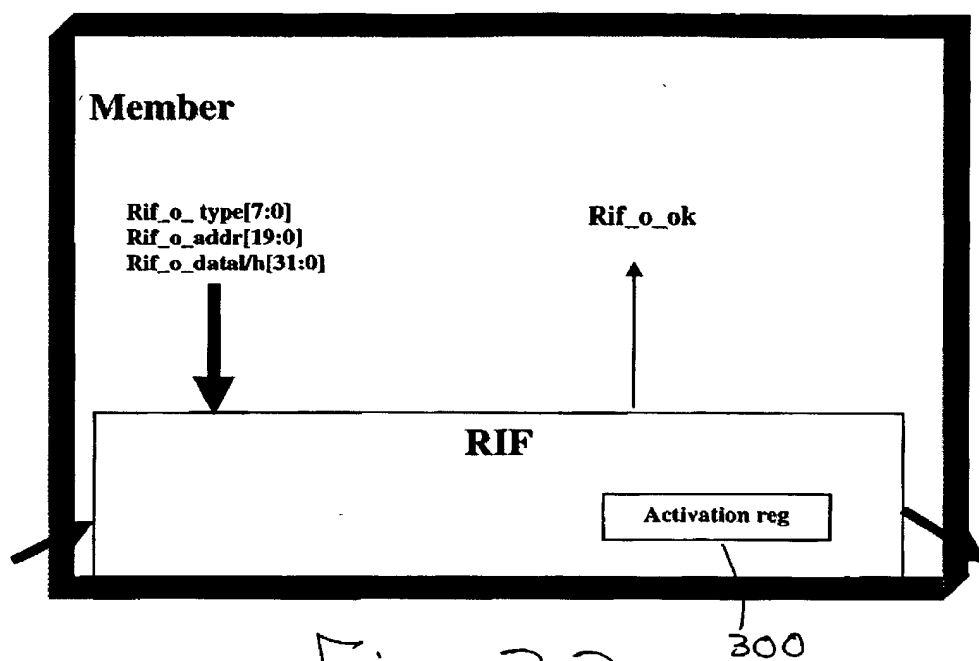


Fig. 32

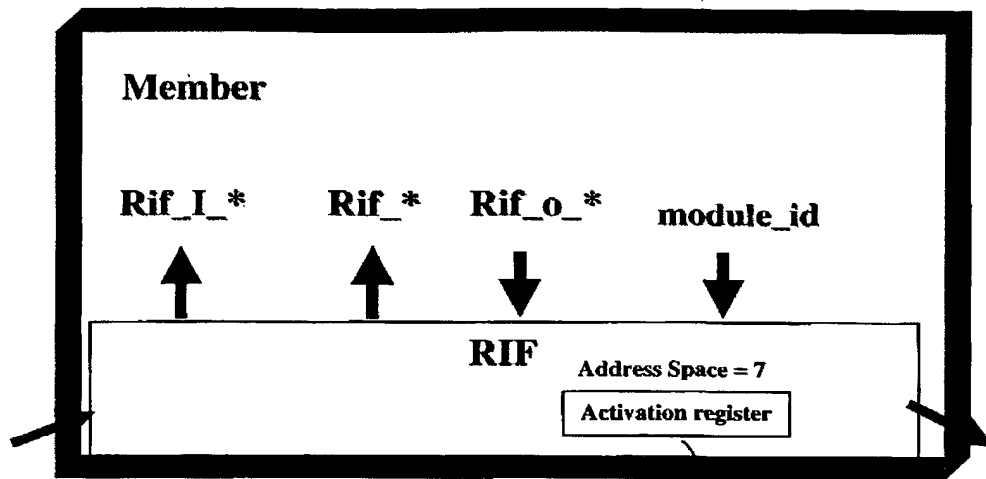
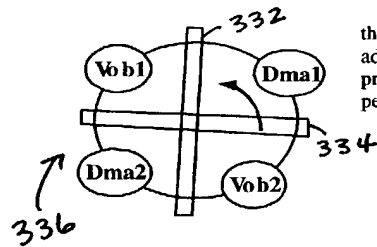


Fig. 33

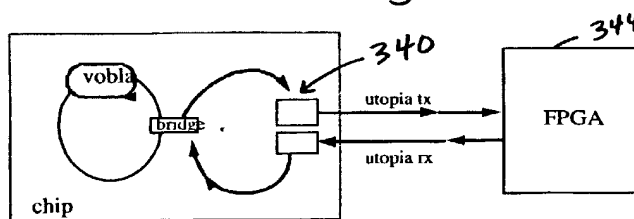
300

Fig. 34



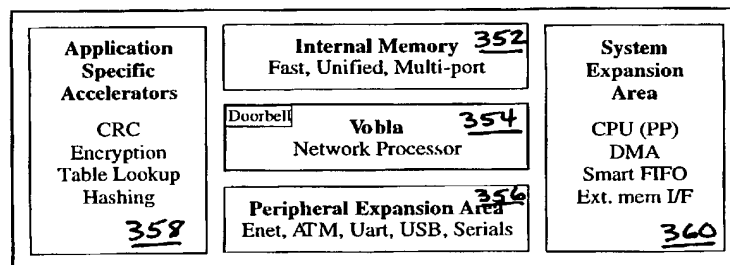
the second land bridge solves most traffic problems, but adds 4 clocks in the overall ring length. This is not a big problem because no message should travel the whole perimeter.

Fig. 35



The utopia interface is forced into mode that communicates in messages, not cells. We using the I/O and maybe some of the logic.

Fig. 36



350

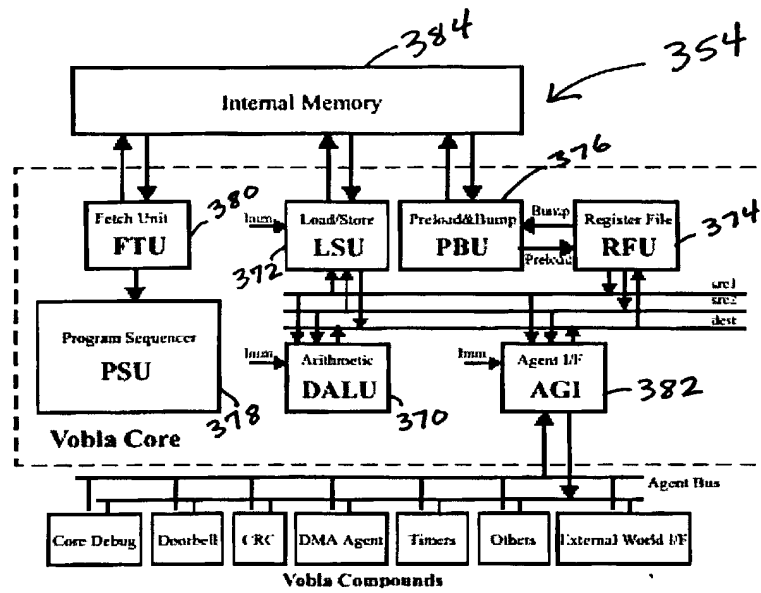
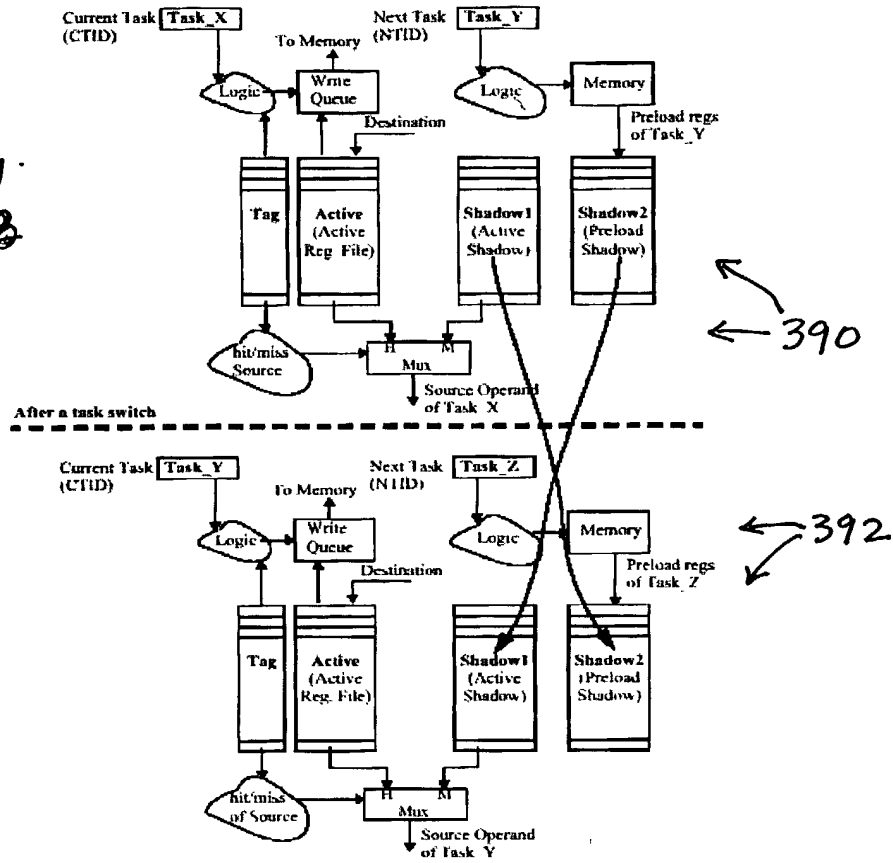
Fig.  
37

Fig.  
38

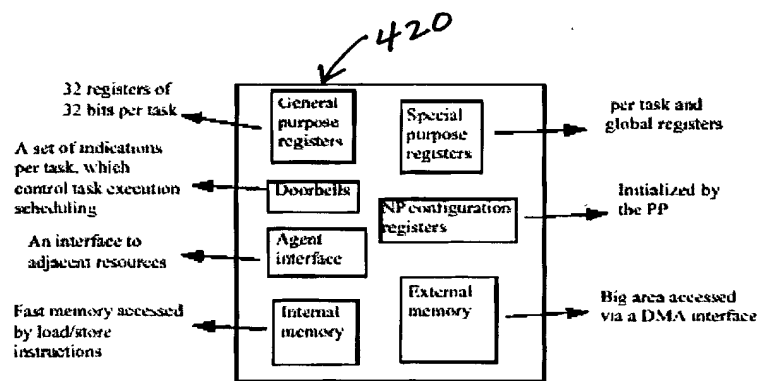
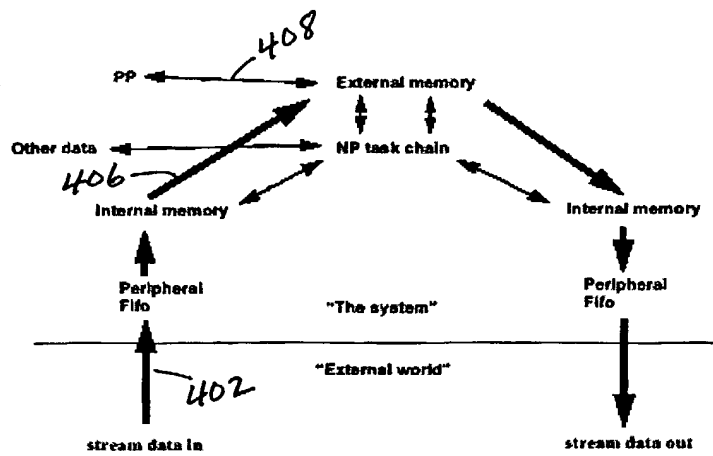


Fig. 41

R1 register:



a - sticky bit  
 eq - equal/zero  
 lt - less than/negative  
 gt - greater than/positive  
 c - carry  
 mb - reflection of the RAM multi-reader busy indication.

430

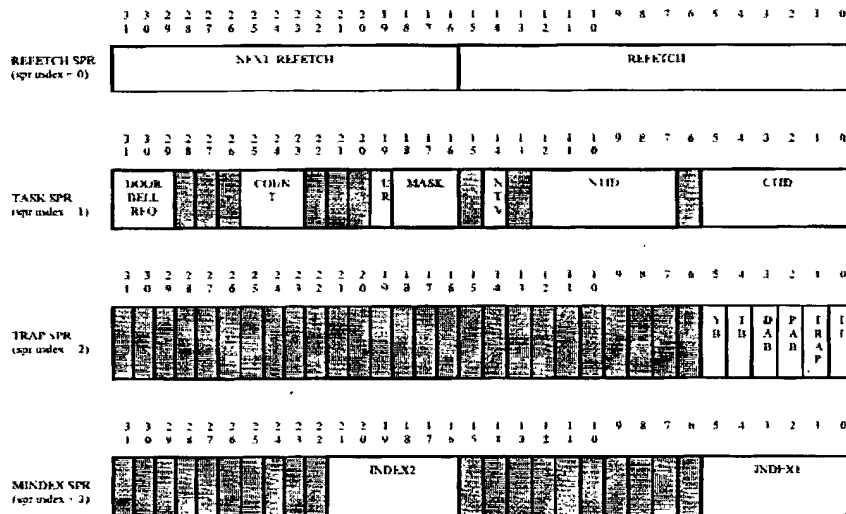
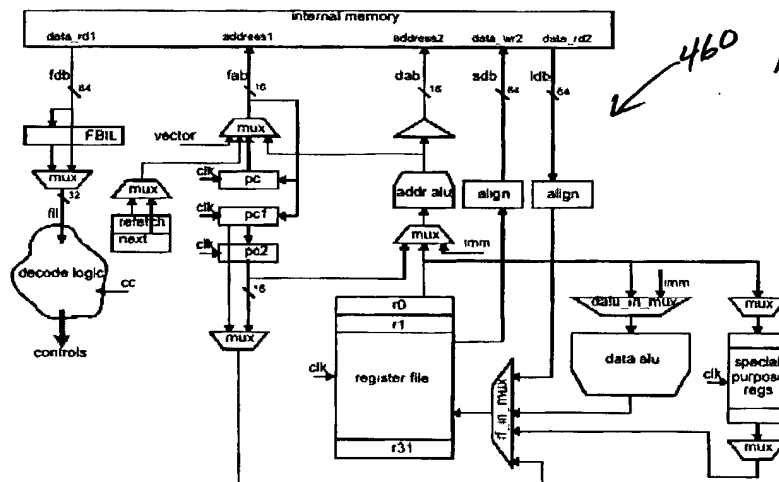
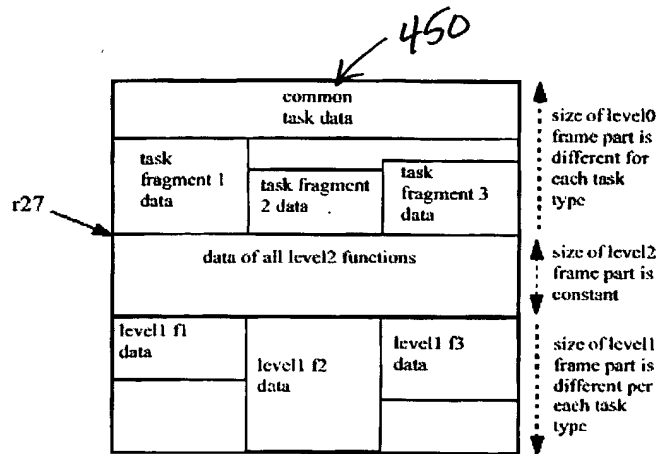


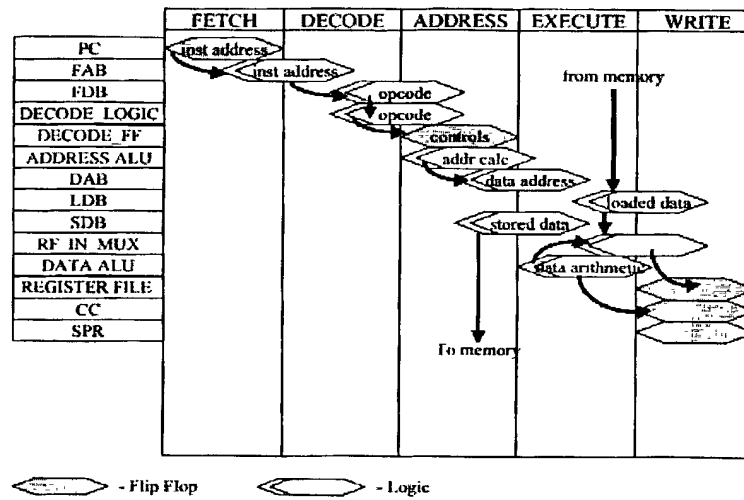
Fig. 42



Frame structure  
of an example  
task type

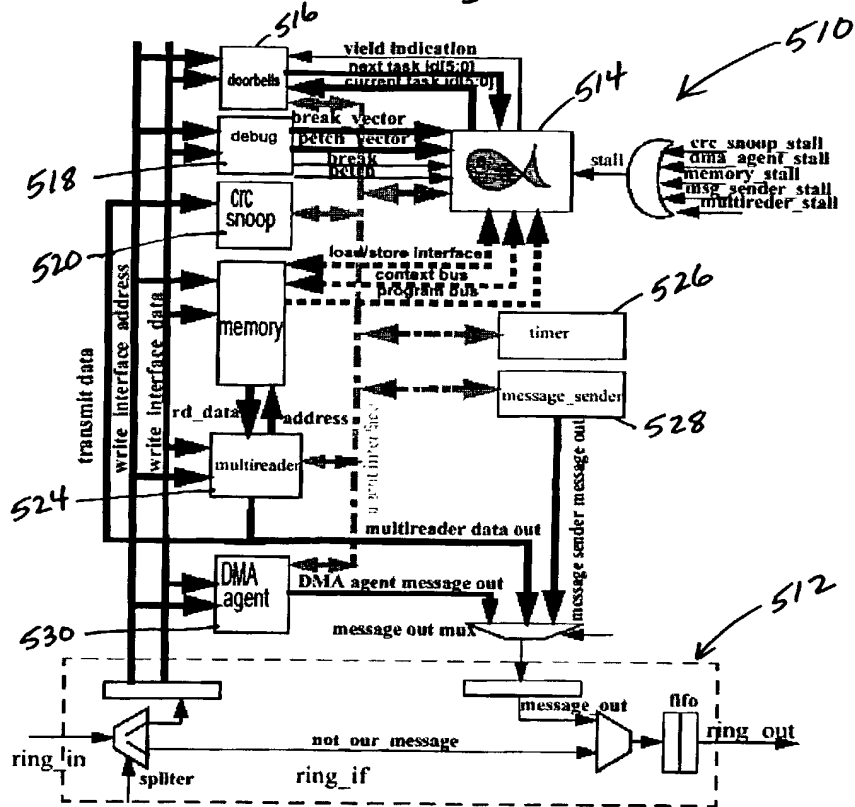
Fig.  
43





[illegible]

Fig. 47



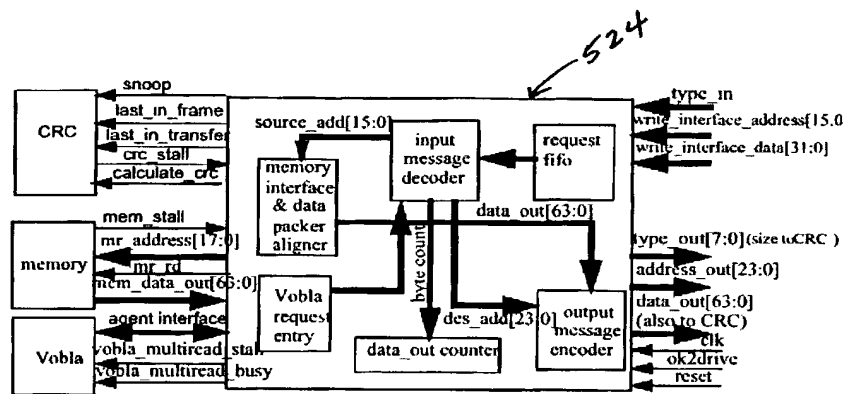


Fig. 48

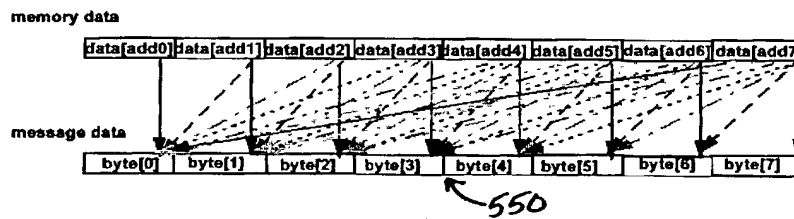


Fig. 49

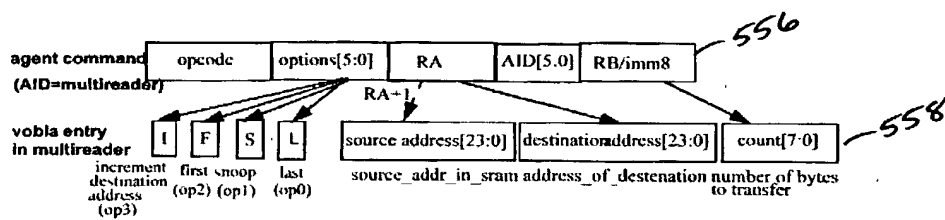


Fig. 50

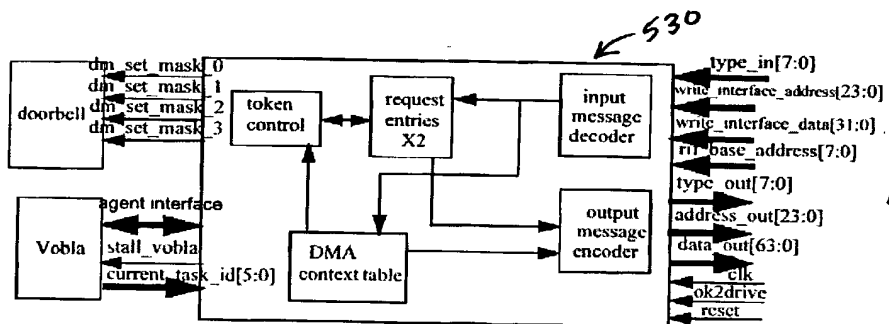
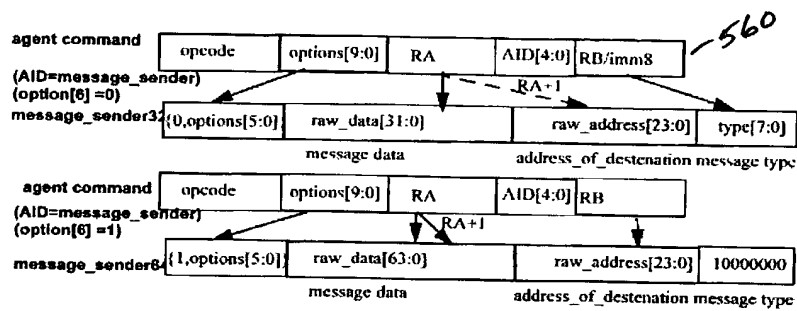


Fig. 54

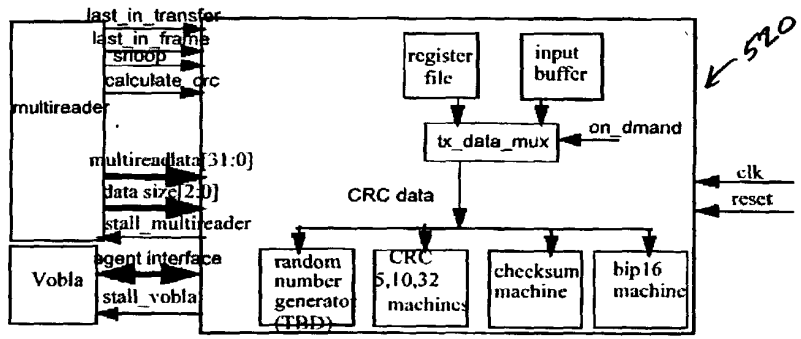
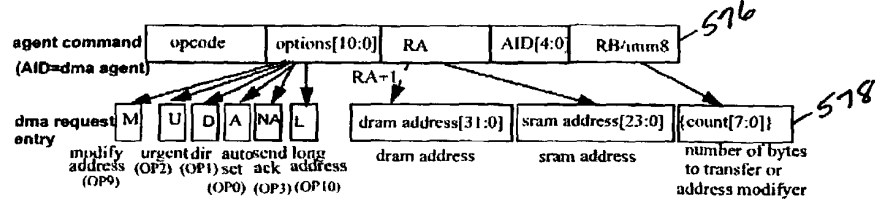
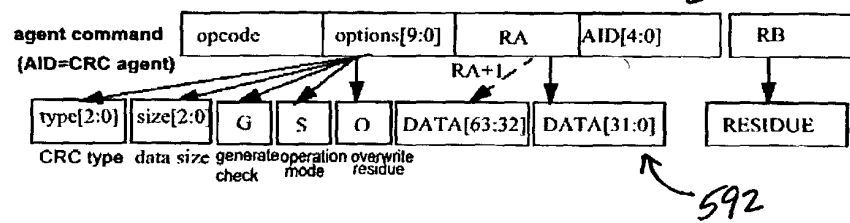


Fig. 55

Fig. 56



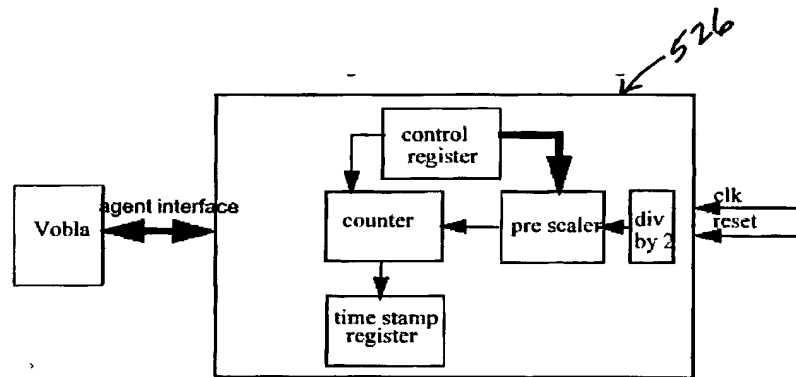


Fig. 57

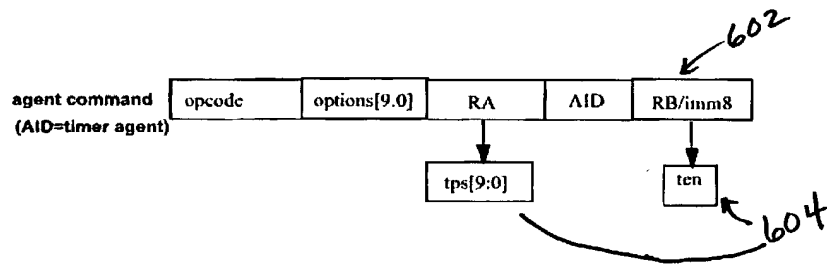


Fig. 58



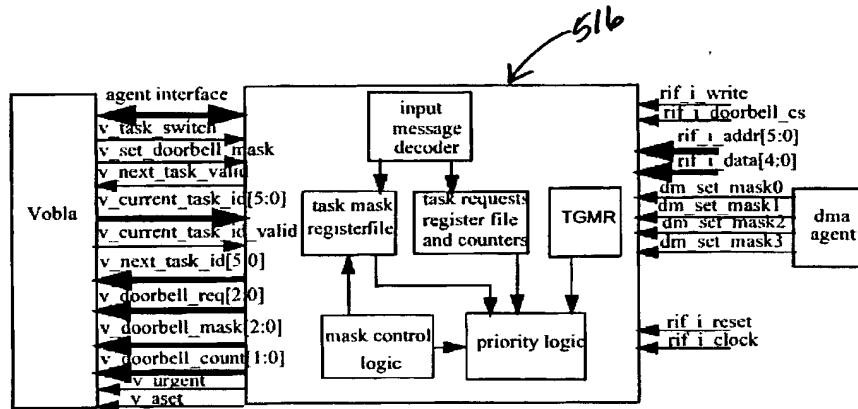


Fig. 59

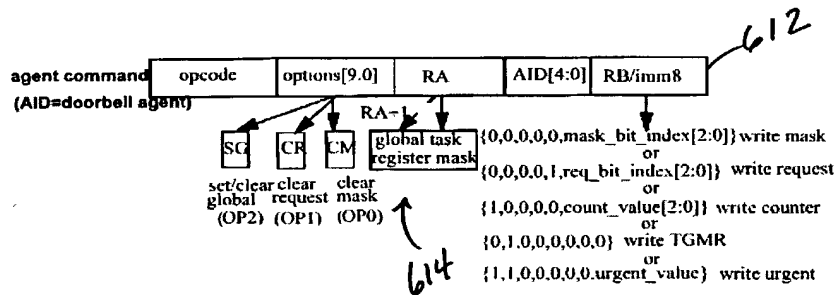
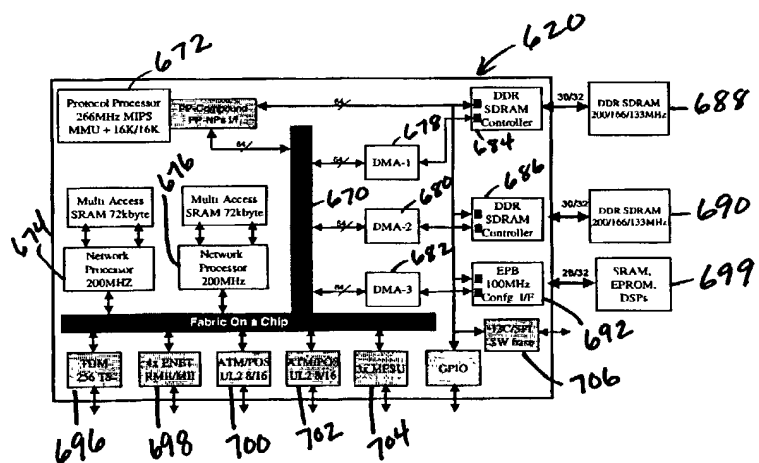
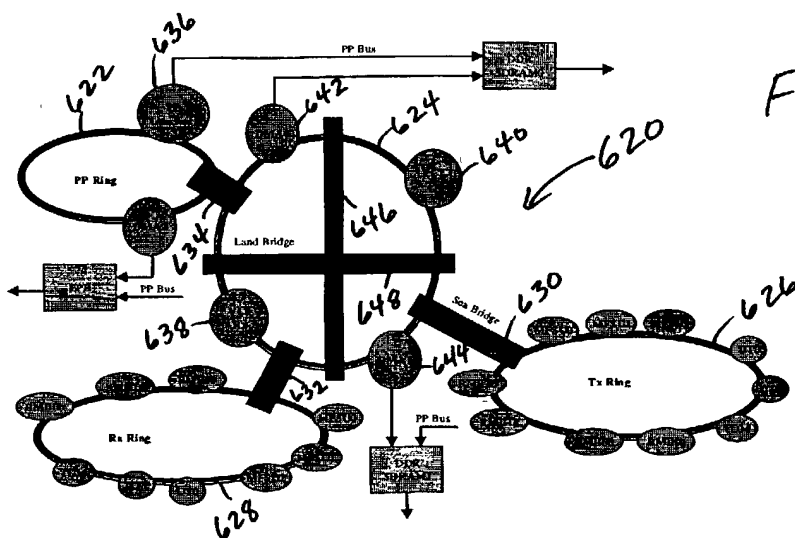
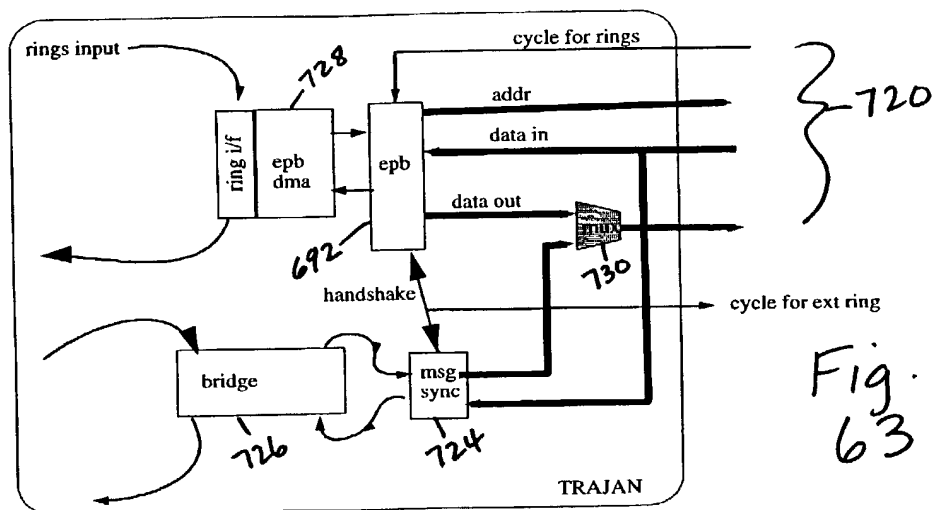


Fig. 60





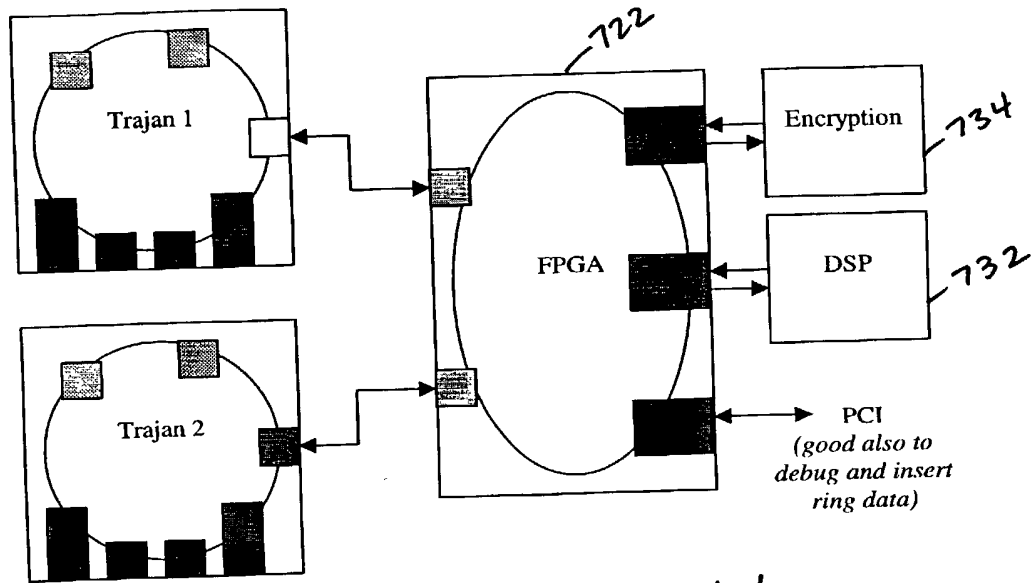


Fig. 64




-  Processor
-  Functional unit
-  External ring interface

Fig. 65

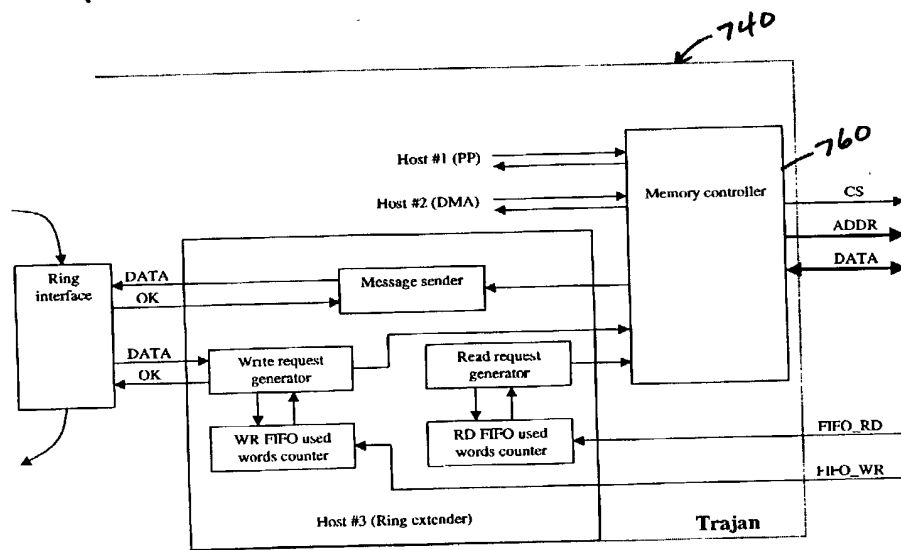
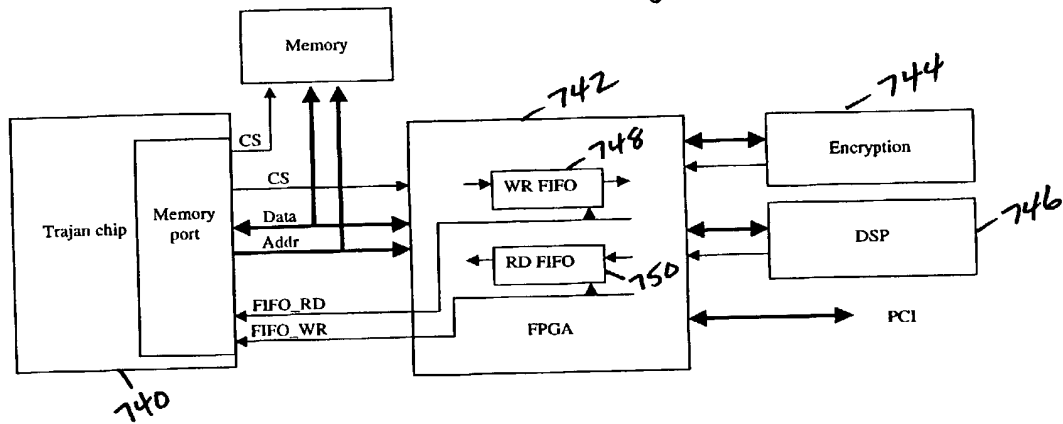


Fig. 66

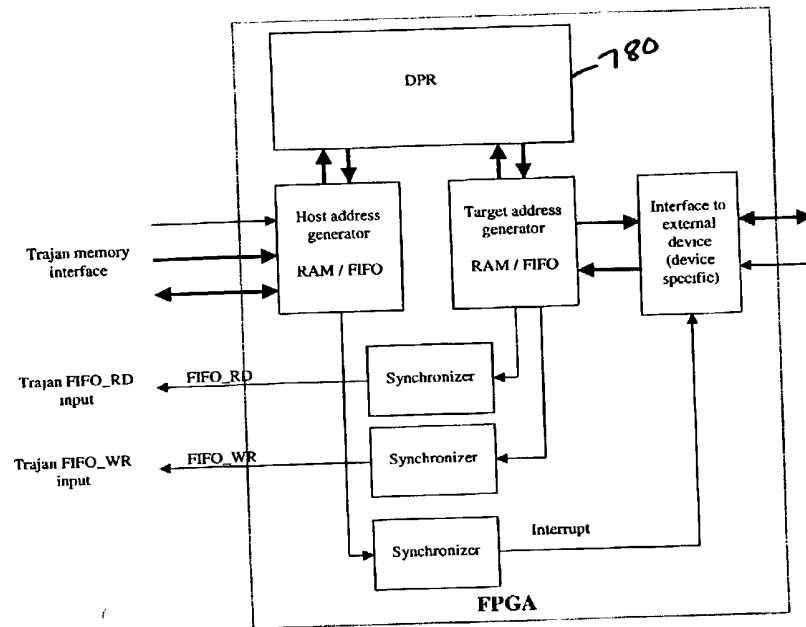


Fig. 67

Fig. 68

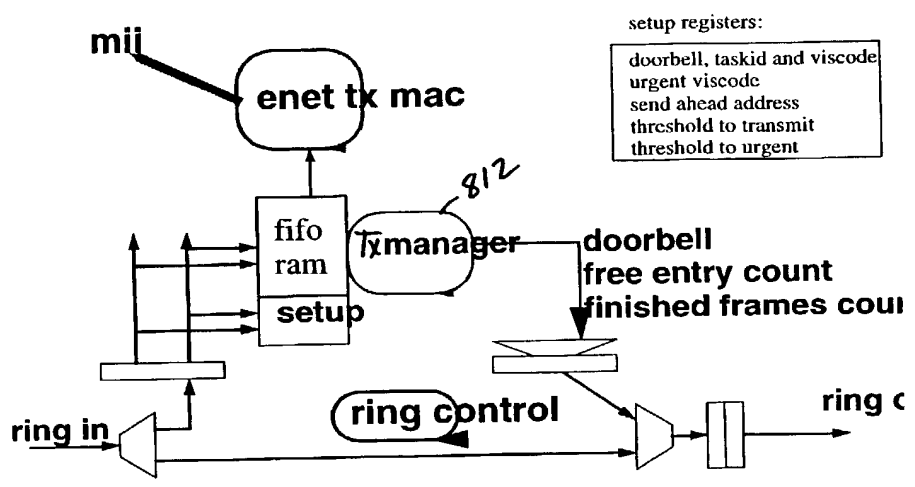


Fig. 69

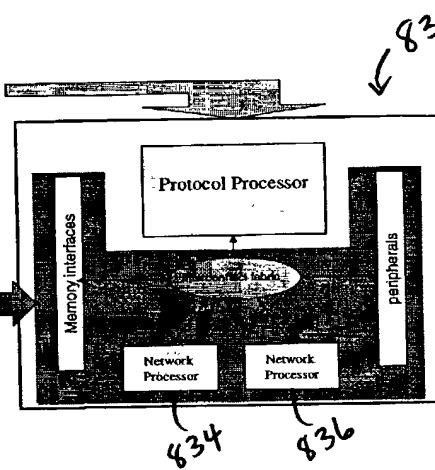
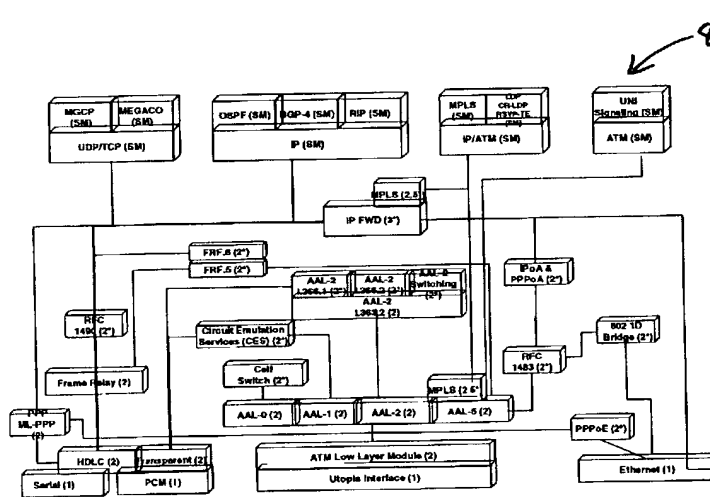


**Control Plane**

Signaling Protocols  
Protocol Management  
Exception Handling  
System Control &  
Configuration

**Data Plane**

Perpacket handling  
Forwarding Decision  
Classification  
QoS Handling  
Queuing  
Scheduling  
Formatting

Fig.  
70Fig.  
71

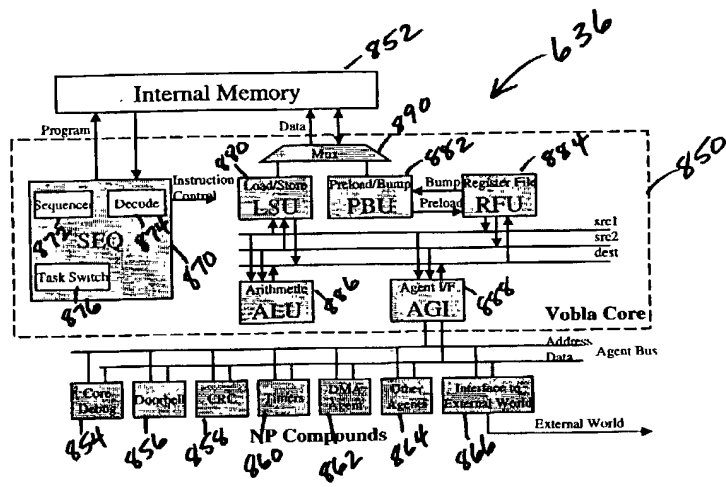


Fig. 72

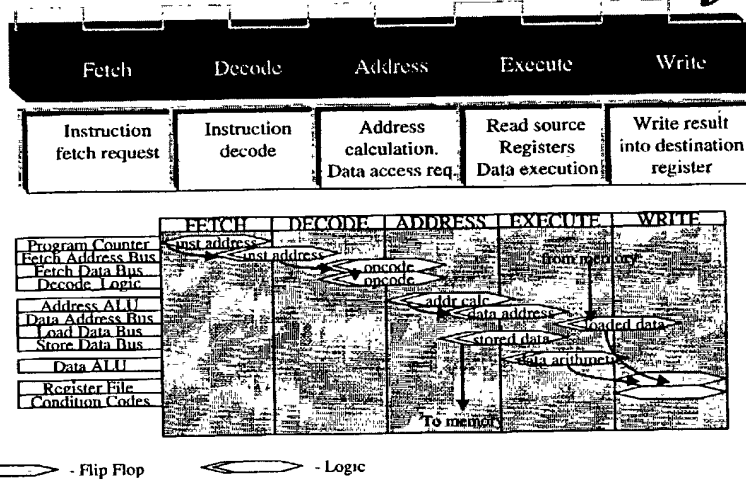
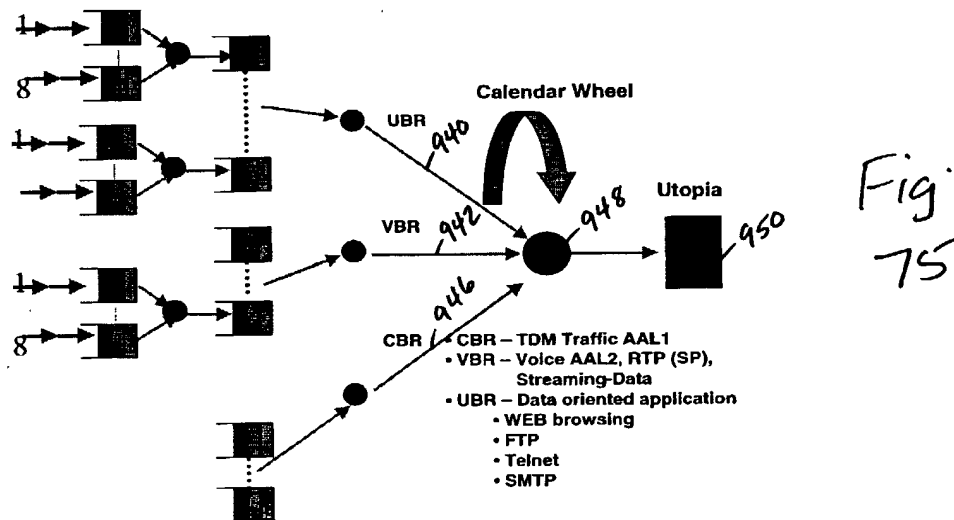
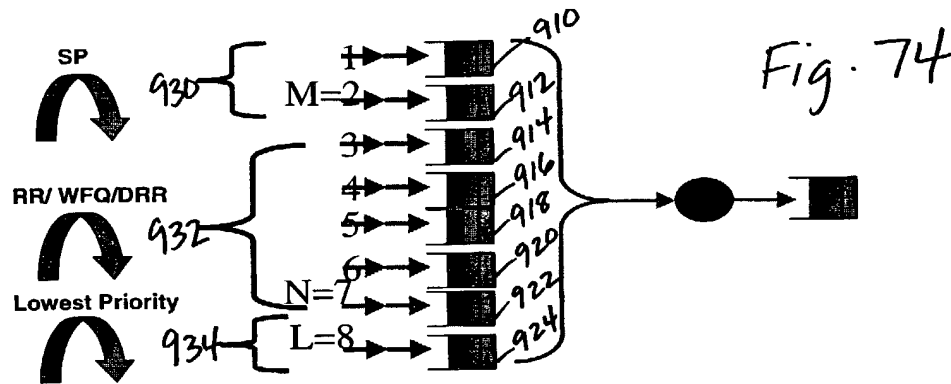
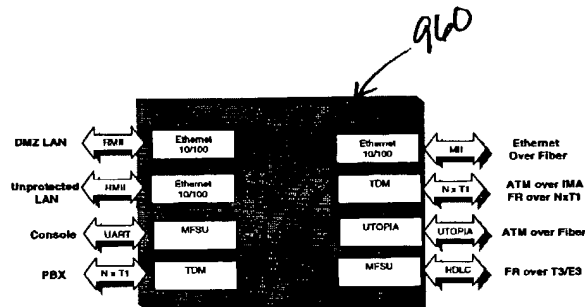
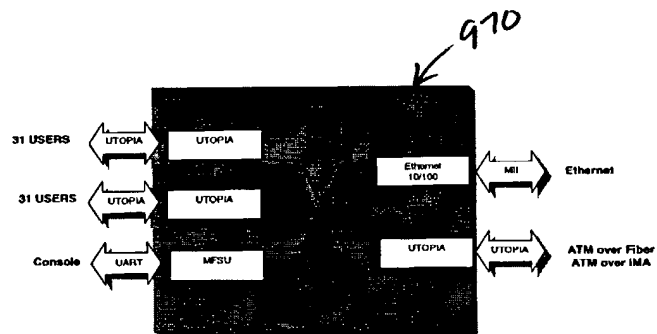
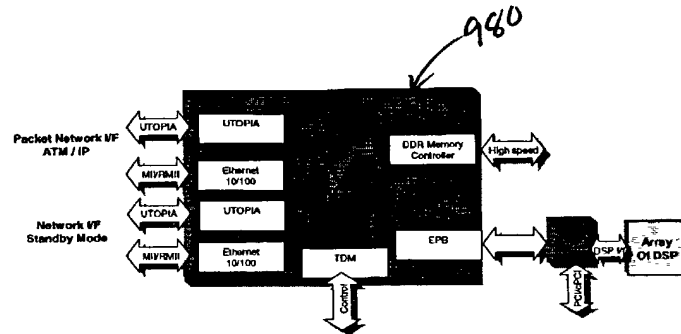
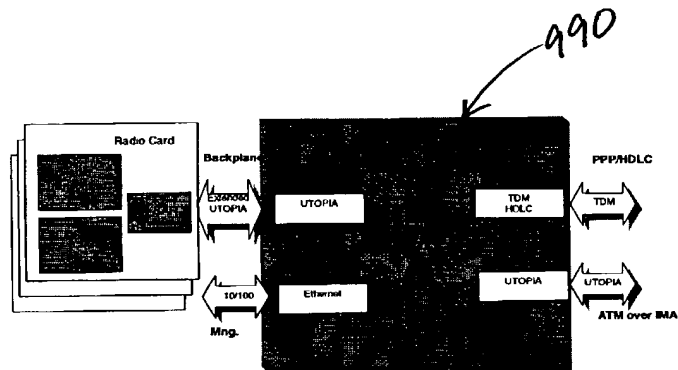


Fig. 73



Fig.  
76Fig.  
77

Fig.  
78Fig.  
79

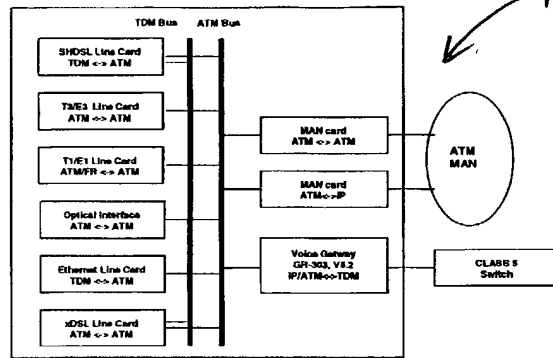


Fig. 80

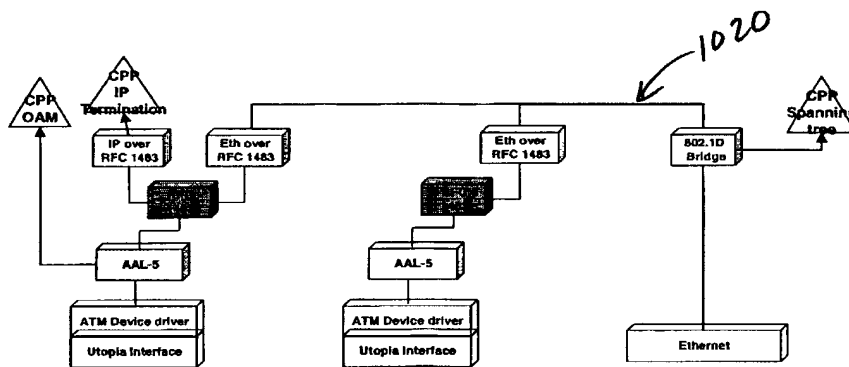


Fig. 81

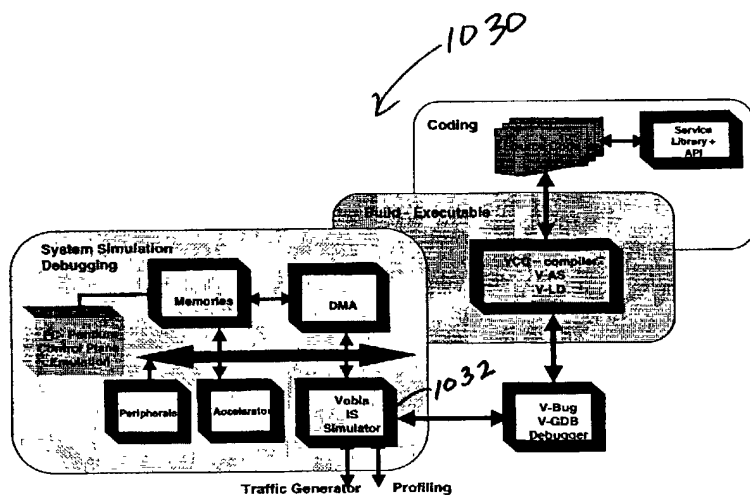


Fig. 82

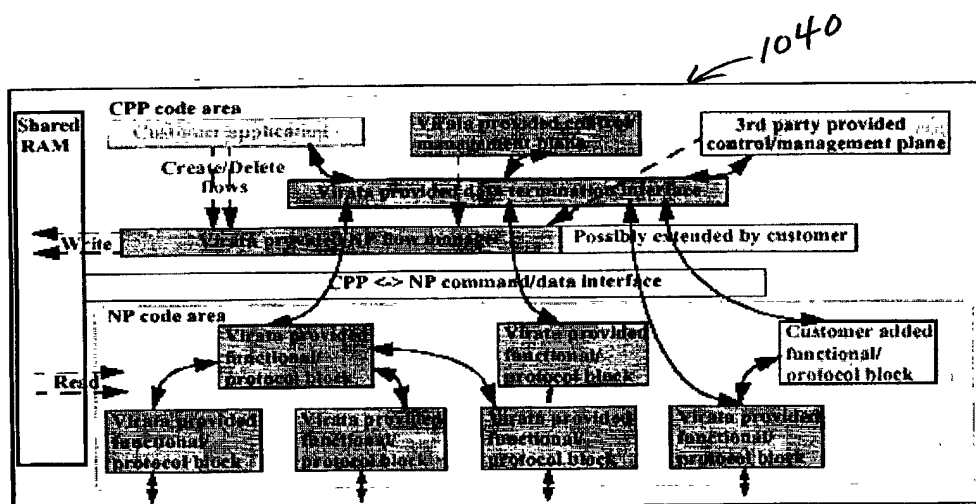


Fig. 83

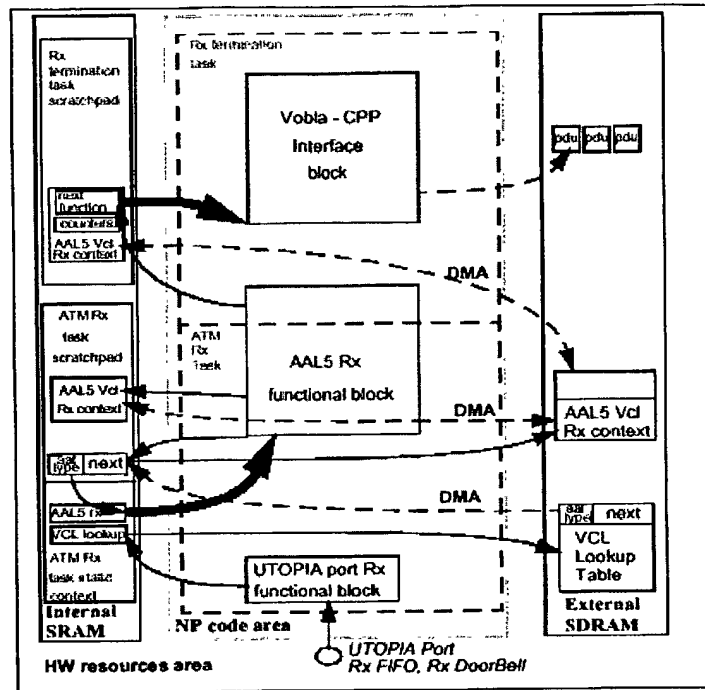
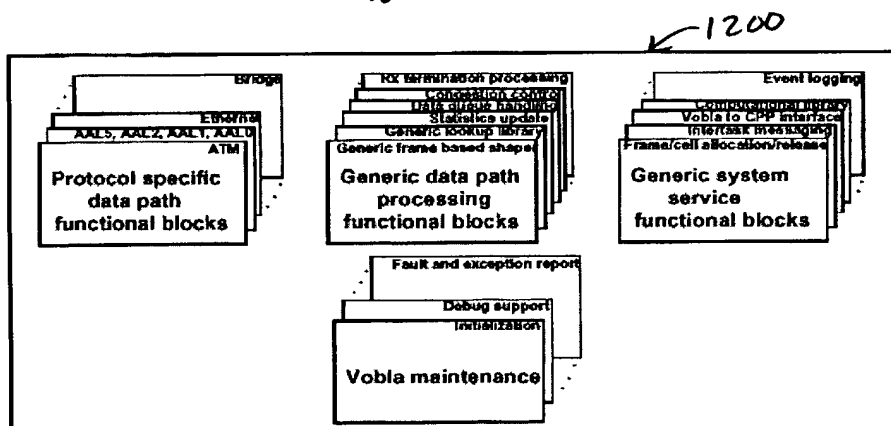
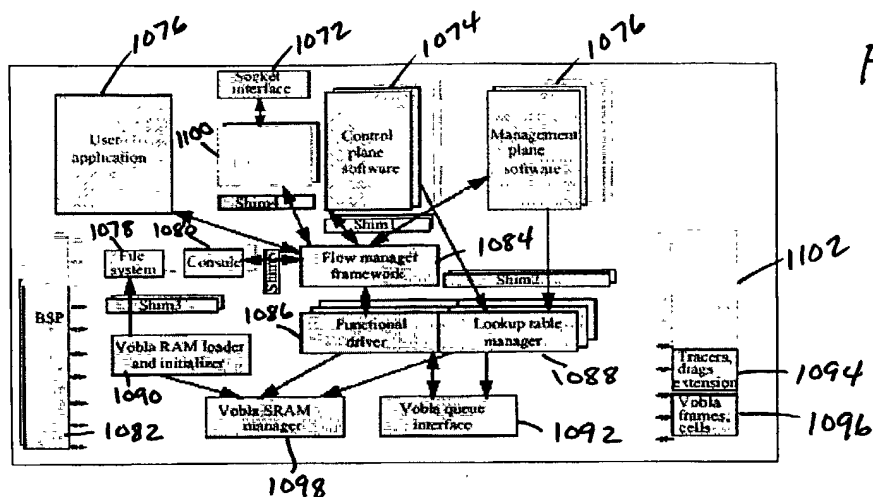


Fig. 84





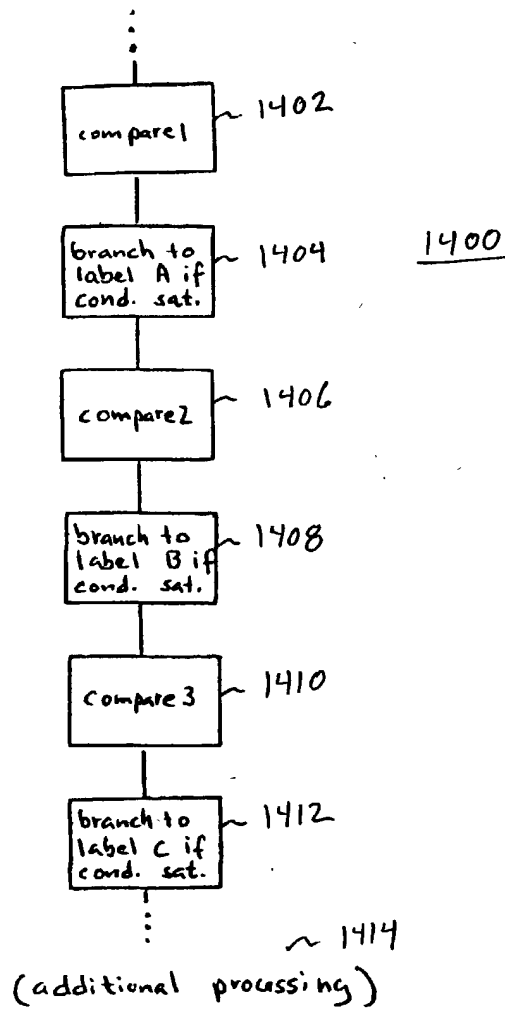


FIG. 87  
(PRIOR ART)

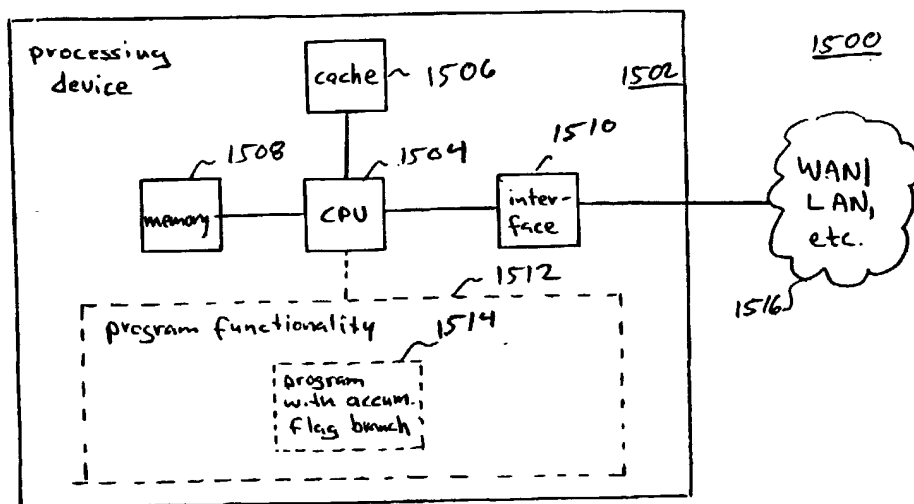


FIG. 88

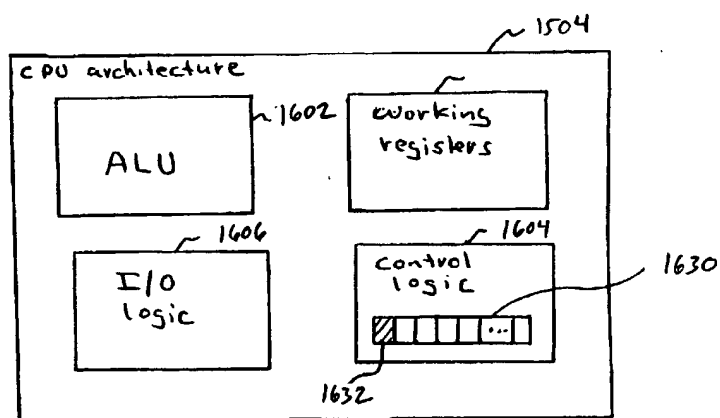


FIG. 89

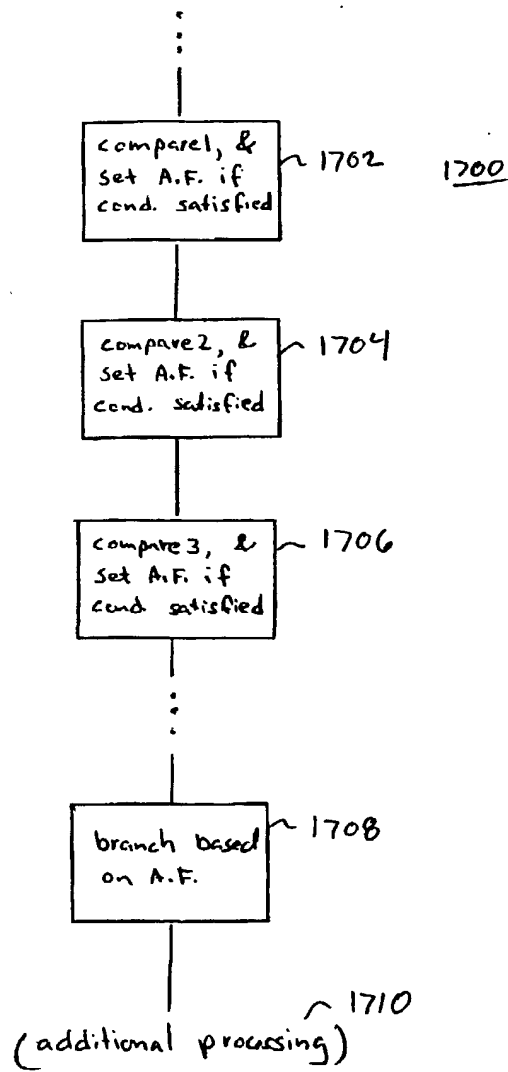


FIG. 90